# nag\_opt\_one\_var\_no\_deriv (e04abc)

### 1. Purpose

**nag\_opt\_one\_var\_no\_deriv (e04abc)** searches for a minimum, in a given finite interval, of a continuous function of a single variable, using function values only. The method (based on quadratic interpolation) is intended for functions which have a continuous first derivative (although it will usually work if the derivative has occasional discontinuities).

# 2. Specification

```
#include <nag.h>
#include <nage04.h>
```

# 3. Description

nag\_opt\_one\_var\_no\_deriv is applicable to problems of the form:

Minimize F(x) subject to  $a \le x \le b$ .

It normally computes a sequence of x values which tend in the limit to a minimum of F(x) subject to the given bounds. It also progressively reduces the interval [a, b] in which the minimum is known to lie. It uses the safeguarded quadratic-interpolation method described in Gill and Murray (1973).

The user must supply a function **funct** to evaluate F(x). The parameters **e1** and **e2** together specify the accuracy

 $Tol(x) = \mathbf{e1} \times |x| + \mathbf{e2}$ 

to which the position of the minimum is required. Note that **funct** is never called at any point which is closer than Tol(x) to a previous point.

If the original interval [a, b] contains more than one minimum, nag\_opt\_one\_var\_no\_deriv will normally find one of the minima.

# 4. Parameters

# funct

The function **funct**, supplied by the user, must calculate the value of F(x) at any point x in [a, b].

The specification of **funct** is:

void funct(double xc, double *fc, Nag_Comm *comm)
<b>xc</b> Input: x, the point at which the value of $F(x)$ is required.
fc Output: the value of the function $F$ at the current point $x$ .
comm
Pointer to structure of type Nag_Comm; the following members are relevant t funct.
<pre>first - Boolean Input: will be set to TRUE on the first call to funct and FALSE for a subsequent calls.</pre>
<b>nf</b> – Integer Input: the number of calls made to <b>funct</b> so far.
$\mathbf{user} - \mathrm{double}  *$
iuser – Integer *
$\mathbf{p}$ - Pointer The type Deinter will be with a C compiler that defines with
The type Pointer will be void * with a C compiler that defines void and char * otherwise.
Before calling nag_opt_one_var_no_deriv these pointers may be allocate memory by the user and initialized with various quantities for use by <b>func</b> when called from nag_opt_one_var_no_deriv.

bf Note: **funct** should be tested separately before being used in conjunction with nag\_opt\_one\_var\_no\_deriv.

#### $\mathbf{e1}$

Input: the relative accuracy to which the position of a minimum is required. (Note that since **e1** is a relative tolerance, the scaling of x is automatically taken into account.)

It is recommended that **e1** should be no smaller than  $2\epsilon$ , and preferably not much less than  $\sqrt{\epsilon}$ , where  $\epsilon$  is the **machine precision**.

If **e1** is set to a value less than  $\epsilon$ , its value is ignored and the default value of  $\sqrt{\epsilon}$  is used instead. In particular, the user may set **e1** = 0.0 to ensure that the default value is used.

### $\mathbf{e2}$

Input: the absolute accuracy to which the position of a minimum is required. It is recommended that  $e^2$  should be no smaller than  $2\epsilon$ .

If **e2** is set to a value less than  $\epsilon$ , its value is ignored and the default value of  $\sqrt{\epsilon}$  is used instead. In particular, the user may set **e2** = 0.0 to ensure that the default value is used.

#### a

Input: the lower bound a of the interval containing a minimum. Output: an improved lower bound on the position of the minimum.

#### b

Input: the upper bound b of the interval containing a minimum. Output: an improved upper bound on the position of the minimum. Constraint:  $\mathbf{b} > \mathbf{a} + \mathbf{e2}$ . Note that the value  $\mathbf{e2} = \sqrt{\epsilon}$  applies here if  $\mathbf{e2} < \epsilon$  on entry to nag\_opt\_one\_var\_no\_deriv.

### max\_fun

Input: the maximum number of function evaluations (calls to **funct**) which the user is prepared to allow.

The number of evaluations actually performed by  $nag_opt_one_var_no_deriv$  may be determined by supplying a non-NULL parameter **comm** (see below) and examining the structure member **nf** on exit.

Constraint:  $\max_{fun} \ge 3$ . (Few problems will require more than 30 function evaluations.)

х

Output: the estimated position of the minimum.

#### f

Output: the value of F at the final point  $\mathbf{x}$ .

#### comm

Input/Output: structure containing pointers for communication to user-supplied functions; see the above description of **funct** for details. The number of times the function **funct** was called is returned in the member **nf**.

If the user does not need to make use of this communication feature, the null pointer NAGCOMM\_NULL may be used in the call to nag\_opt\_one\_var\_no\_deriv; comm will then be declared internally for use in calls to user-supplied functions.

fail

The NAG error parameter, see the Essential Introduction to the NAG C Library.

### 5. Error Indications and Warnings

# NE\_2\_REAL\_ARG\_GE

On entry,  $\mathbf{a}+\mathbf{e2} = \langle value \rangle$  while  $\mathbf{b} = \langle value \rangle$ . These parameters must satisfy  $\mathbf{a}+\mathbf{e2} < \mathbf{b}$ .

# NE\_INT\_ARG\_LT

On entry, **max\_fun** must not be less than 3: **max\_fun** =  $\langle value \rangle$ .

### NW\_MAX\_FUN

The maximum number of function calls,  $\langle value \rangle$ , have been performed.

This may have happened simply because **max\_fun** was set too small for a particular problem, or may be due to a mistake in the user-supplied function, **funct**. If no mistake can be found in **funct**, restart nag\_opt\_one\_var\_no\_deriv (preferably with the values of **a** and **b** given on exit from the previous call to nag\_opt\_one\_var\_no\_deriv).

#### 6. Further Comments

Timing depends on the behaviour of F(x), the accuracy demanded, and the length of the interval [a,b]. Unless F(x) can be evaluated very quickly, the run time will usually be dominated by the time spent in **funct**.

If F(x) has more than one minimum in the original interval [a, b], nag\_opt\_one\_var\_no\_deriv will determine an approximation x (and improved bounds a and b) for one of the minima.

If nag\_opt\_one\_var\_no\_deriv finds an x such that  $F(x - \delta_1) > F(x) < F(x + \delta_2)$  for some  $\delta_1, \delta_2 \geq Tol(x)$ , the interval  $[x - \delta_1, x + \delta_2]$  will be regarded as containing a minimum, even if F(x) is less than  $F(x - \delta_1)$  and  $F(x + \delta_2)$  only due to rounding errors in the user-supplied function. Therefore **funct** should be programmed to calculate F(x) as accurately as possible, so that nag\_opt\_one\_var\_no\_deriv will not be liable to find a spurious minimum.

### 6.1. Accuracy

If F(x) is  $\delta$ -unimodal for some  $\delta < Tol(x)$ , where  $Tol(x) = \mathbf{e1} \times |x| + \mathbf{e2}$ , then, on exit, x approximates the minimum of F(x) in the original interval [a, b] with an error less than  $3 \times Tol(x)$ .

### 6.2. References

Gill P E and Murray W (1973) Safeguarded steplength algorithms for optimization using descent methods, NPL Report NAC 37, National Physical Laboratory.

### 7. See Also

nag\_opt\_one\_var\_deriv (e04bbc)

# 8. Example

A sketch of the function

$$F(x) = \frac{\sin x}{x}$$

shows that it has a minimum somewhere in the range [3.5, 5.0]. The example program below shows how nag\_opt\_one\_var\_no\_deriv can be used to obtain a good approximation to the position of a minimum.

### 8.1. Program Text

```
/* nag_opt_one_var_no_deriv(e04abc) Example Program.
 * Copyright 1998 Numerical Algorithms Group.
 * Mark 5, 1998.
 */
#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <math.h>
#include <nage04.h>
#ifdef NAG_PROTO
static void funct(double xc, double *fc, Nag_Comm *comm);
#else
static void funct();
#endif
#ifdef NAG_PROTO
static void funct(double xc, double *fc, Nag_Comm *comm)
#else
static void funct(xc, fc, comm)
     double xc, *fc;
     Nag_Comm *comm;
#endif
ł
  *fc = sin(xc) / xc;
}
/* funct */
main()
ł
  double a, b;
  double e1, e2;
  double x, f;
  Integer max_fun;
  Nag_Comm comm;
  static NagError fail;
  Vprintf("e04abc Example Program Results.\n\n");
  /* e1 and e2 are set to zero so that e04abc will reset them to
    their default values
   *
  */
  e1 = 0.0;
  e2 = 0.0;
  /* The minimum is known to lie in the range (3.5, 5.0) */ a = 3.5;
  b = 5.0;
  /* Allow 30 calls of funct */
  max_fun = 30;
  fail.print = TRUE;
  e04abc(funct, e1, e2, &a, &b, max_fun, &x, &f, &comm, &fail);
  Vprintf("The minimum lies in the interval \%7.5f to \%7.5f.\n", a, b);
  Vprintf("Its estimated position is %7.5f,\n", x);
```

Vprintf("where the function value is %9.4e.\n",f); Vprintf("%11d function evaluations were required.\n", comm.nf);

```
exit(EXIT_SUCCESS);
}
```

### 8.2. Program Data

None.

# 8.3. Program Results

e04abc Example Program Results.

The minimum lies in the interval 4.49341 to 4.49341. Its estimated position is 4.49341, where the function value is -2.1723e-01. 10 function evaluations were required.