# nag\_real\_apply\_q (f01qdc)

## 1. Purpose

nag\_real\_apply\_q (f01qdc) performs one of the transformations

 $B := QB \quad \text{or} \quad B := Q^T B,$ 

where B is an m by *ncolb* real matrix and Q is an m by m orthogonal matrix, given as the product of Householder transformation matrices.

This function is intended for use following nag\_real\_qr (f01qcc).

## 2. Specification

```
#include <nag.h>
#include <nagf01.h>
```

## 3. Description

Q is assumed to be given by

$$Q = (Q_n Q_{n-1} \dots Q_1)^T,$$

 $Q_k$  being given in the form

$$Q_k = \begin{pmatrix} I & 0 \\ 0 & T_k \end{pmatrix},$$

where

$$\begin{split} T_k &= I - u_k u_k^2 \\ u_k &= \begin{pmatrix} \zeta_k \\ z_k \end{pmatrix}, \end{split}$$

 $\zeta_k$  is a scalar and  $z_k$  is an (m-k) element vector.  $z_k$  must be supplied in the (k-1)th column of **a** in elements  $\mathbf{a}[k][k-1], \ldots, \mathbf{a}[m-1][k-1]$  and  $\zeta_k$  must be supplied either in  $\mathbf{a}[k-1][k-1]$  or in  $\mathbf{zeta}[k-1]$ , depending upon the parameter wheret.

To obtain Q explicitly B may be set to I and premultiplied by Q. This is more efficient than obtaining  $Q^T$ .

## 4. Parameters

trans

Input: the operation to be performed as follows:

trans = NoTranspose, perform the operation B := QB.

trans = Transpose or ConjugateTranspose, perform the operation  $B := Q^T B$ .

Constraint: trans must be one of NoTranspose, Transpose or ConjugateTranspose.

#### wheret

Input: indicates where the elements of  $\zeta$  are to be found as follows:

where t = Nag Elements In, the elements of  $\zeta$  are in a.

where  $t = Nag\_ElementsSeparate$ , the elements of  $\zeta$  are separate from a, in zeta. Constraint: where t must be Nag\\_ElementsIn or Nag\\_ElementsSeparate.

#### $\mathbf{m}$

Input: m, the number of rows of A. Constraint:  $\mathbf{m} \geq \mathbf{n}$ .

#### $\mathbf{n}$

Input: n, the number of columns of A. When  $\mathbf{n} = 0$  then an immediate return is effected. Constraint:  $\mathbf{n} \ge 0$ .

## a[m][tda]

Input: the leading m by n strictly lower triangular part of the array **a** must contain details of the matrix Q. In addition, when **wheret** = **Nag\_ElementsIn**, then the diagonal elements of **a** must contain the elements of  $\zeta$  as described under the parameter **zeta** below.

When where  $t = Nag\_ElementsSeparate$ , the diagonal elements of the array a are referenced, since they are used temporarily to store the  $\zeta_k$ , but they contain their original values on return.

#### tda

Input: the second dimension of the array  $\mathbf{a}$  as declared in the function from which nag\_real\_apply\_q is called.

Constraint:  $\mathbf{tda} \geq \mathbf{n}$ .

#### zeta[n]

Input: if where  $t = Nag\_ElementsSeparate$ , the array zeta must contain the elements of  $\zeta$ . If zeta[k-1] = 0.0 then  $T_k$  is assumed to be I otherwise zeta[k-1] is assumed to contain  $\zeta_k$ . When where  $t = Nag\_ElementsIn$ , zeta is not referenced and may be set to the null pointer, i.e., (double \*)0.

#### ncolb

Input: *ncolb*, the number of columns of *B*. When **ncolb** = 0 then an immediate return is effected. Constraint: **ncolb**  $\geq 0$ .

#### b[m][tdb]

Input: the leading m by *ncolb* part of the array **b** must contain the matrix to be transformed. Output: **b** is overwritten by the transformed matrix.

#### $\mathbf{tdb}$

Input: the second dimension of the array **b** as declared in the function from which nag\_real\_apply\_q is called. Constraint:  $tdb \ge ncolb$ .

#### fail

The NAG error parameter, see the Essential Introduction to the NAG C Library.

## 5. Error Indications and Warnings

## NE\_BAD\_PARAM

On entry, parameter **trans** had an illegal value. On entry, parameter **wheret** had an illegal value.

#### NE\_2\_INT\_ARG\_LT

On entry,  $\mathbf{m} = \langle value \rangle$  while  $\mathbf{n} = \langle value \rangle$ . These parameters must satisfy  $\mathbf{m} \ge \mathbf{n}$ . On entry,  $\mathbf{tda} = \langle value \rangle$  while  $\mathbf{n} = \langle value \rangle$ . These parameters must satisfy  $\mathbf{tda} \ge \mathbf{n}$ . On entry,  $\mathbf{tdb} = \langle value \rangle$  while  $\mathbf{ncolb} = \langle value \rangle$ . These parameters must satisfy  $\mathbf{tdb} \ge \mathbf{ncolb}$ .

#### NE\_INT\_ARG\_LT

On entry, **n** must not be less than 0:  $\mathbf{n} = \langle value \rangle$ . On entry, **ncolb** must not be less than 0: **ncolb** =  $\langle value \rangle$ .

#### NE\_ALLOC\_FAIL

Memory allocation failed.

## 6. Further Comments

The approximate number of floating-point operations is given by 2n(2m - n)ncolb.

## 6.1. Accuracy

Letting C denote the computed matrix  $Q^T B$ , C satisfies the relation

QC = B + E

where  $||E|| \leq c\epsilon ||B||$ ,  $\epsilon$  is the **machine precision**, c is a modest function of m and ||.|| denotes the spectral (two) norm. An equivalent result holds for the computed matrix QB. See also Section 6.1 of nag\_real\_qr (f01qcc).

## 6.2. References

Golub G H and Van Loan C F (1989) Matrix Computations (2nd Edn) Johns Hopkins University Press, Baltimore.

Wilkinson J H (1965) The Algebraic Eigenvalue Problem Clarendon Press, Oxford.

## 7. See Also

nag\_real\_qr (f01qcc)

## 8. Example

To obtain the matrix  $Q^T B$  for the matrix B given by

	/ 1.10	0.00
	0.90	0.00
B =	0.60	1.32
	0.00	1.10
	-0.80	-0.26/

following the QR factorization of the 5 by 3 matrix A given by

$$A = \begin{pmatrix} 2.0 & 2.5 & 2.5 \\ 2.0 & 2.5 & 2.5 \\ 1.6 & -0.4 & 2.8 \\ 2.0 & -0.5 & 0.5 \\ 1.2 & -0.3 & -2.9 \end{pmatrix}.$$

## 8.1. Program Text

```
/* nag_real_apply_q(f01qdc) Example Program
 * Copyright 1990 Numerical Algorithms Group.
 * Mark 1, 1990.
 */
#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nagf01.h>
#define MMAX 20
#define NMAX 10
#define NCBMAX 5
main()
  Integer tda = NMAX;
  Integer tdb = NCBMAX;
  double zeta[NMAX], a[MMAX][NMAX], b[MMAX][NCBMAX];
  Integer i, j, m, n, ncolb;
  Vprintf("f01qdc Example Program Results\n");
  Vscanf(" %*[^\n]"); /* skip headings in data file */
```

```
Vscanf(" %*[^\n]");
  Vscanf("%ld%ld", &m, &n);
  if (m > MMAX || n > NMAX)
    {
      Vprintf("m or n is out of range.\n");
Vprintf("m = %2ld, n = %2ld\n", m, n);
    }
  else
    {
       Vscanf(" %*[^\n]");
      for (i = 0; i < m; ++i)
         for (j = 0; j < n; ++j)
           Vscanf("%lf", &a[i][j]);
      Vscanf(" %*[^\n]");
Vscanf("%ld", &ncolb);
       if (ncolb > NCBMAX)
         {
           Vprintf("ncolb is out of range.\n");
           Vprintf("ncolb = %2ld\n", ncolb);
         }
       else
         {
           Vscanf(" %*[^\n]");
           for (i = 0; i < m; ++i)
for (j = 0; j < ncolb; ++j)</pre>
                Vscanf("%lf", &b[i][j]);
           /* Find the QR factorization of A */
           f01qcc(m, n, (double *)a, tda, zeta, NAGERR_DEFAULT);
           /* Form Q'*B */
           f01qdc(Transpose, Nag_ElementsSeparate, m, n, (double *)a, tda, zeta,
                   ncolb, (double *)b, tdb, NAGERR_DEFAULT);
           Vprintf("Matrix Q'*B\n");
           for (i = 0; i < m; ++i)
              {
                for (j = 0; j < ncolb; ++j)
Vprintf(" %8.4f", b[i][j]);</pre>
                Vprintf("\n");
             }
         }
    }
  exit(EXIT_SUCCESS);
}
```

8.2. Program Data

```
f01qdc Example Program Data
Values of m and n.
 5
       3
Matrix A
 2.0 2.5
2.0 2.5
             2.5
             2.5
 1.6 -0.4
            2.8
 2.0 -0.5
           0.5
 1.2 -0.3 -2.9
Value of ncolb
 2
Matrix B
 1.1 0.0
      0.0
1.32
 0.9
 0.6
      1.1
 0.0
-0.8 -0.26
```

## 8.3. Program Results

f01qdc Example Program Results Matrix Q'\*B -1.0000 -1.0000 -1.0000 1.0000 -1.0000 -1.0000 -0.1000 0.1000 -0.1000 -0.1000