



Simulation Status

LAViSta

Laboratories in **An**necy working on
Vibration **S**tabilization

Catherine ADLOFF

Benoît BOLZON

Franck CADOUX

Yan BASTIAN

Andréa JEREMIE

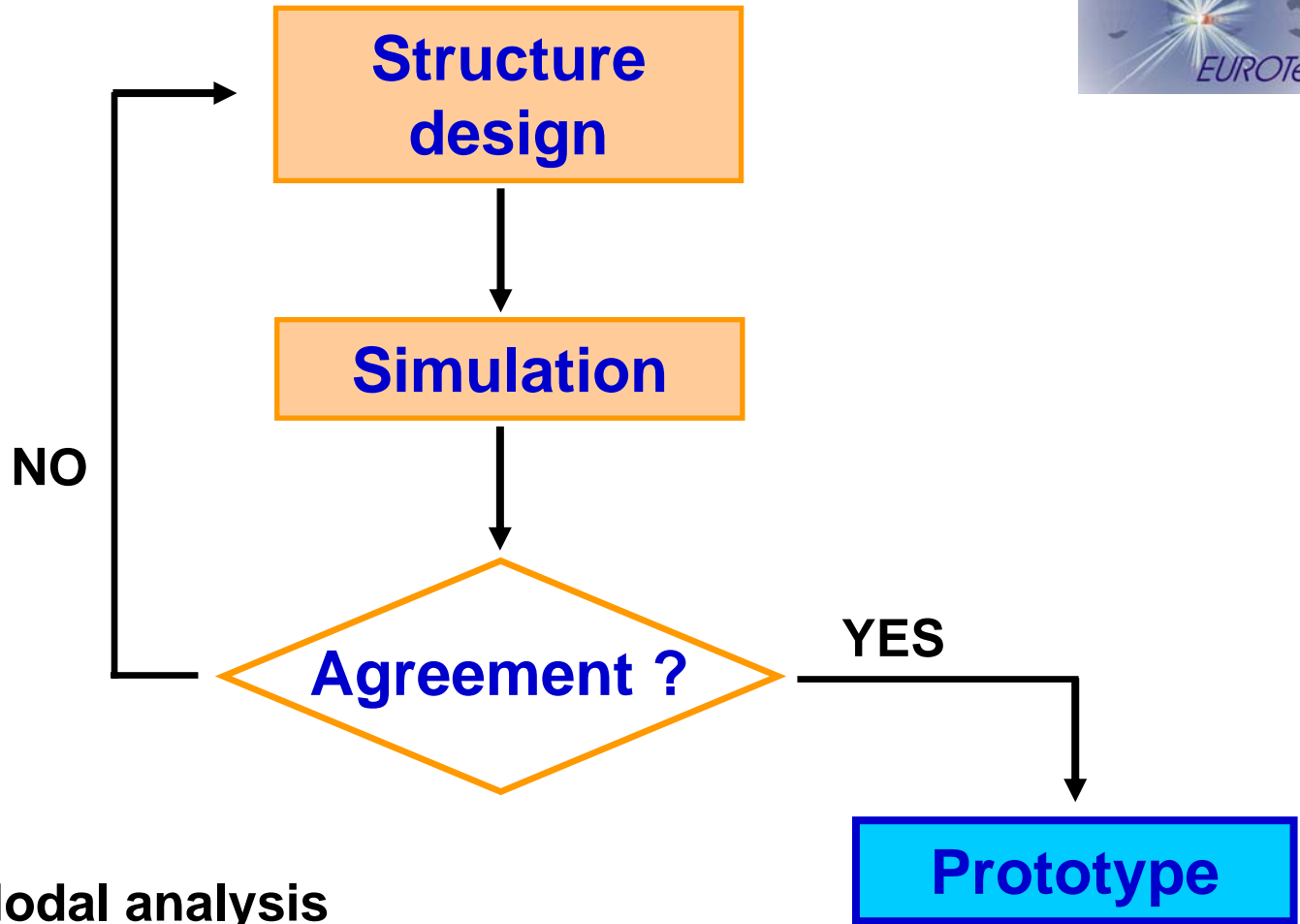
Yannis KARYOTAKIS

Claude GIRARD

Nicolas GEFFROY

Overview

1. Final focus system vibrations
2. Modal analysis
3. Dynamic response predictions
4. Future prospects
5. Conclusions



Simulation : {
Modal analysis
Dynamic response prediction

➔ Improve design before building a prototype

Final focus system vibrations

Excitation spectrum



Structural resonances

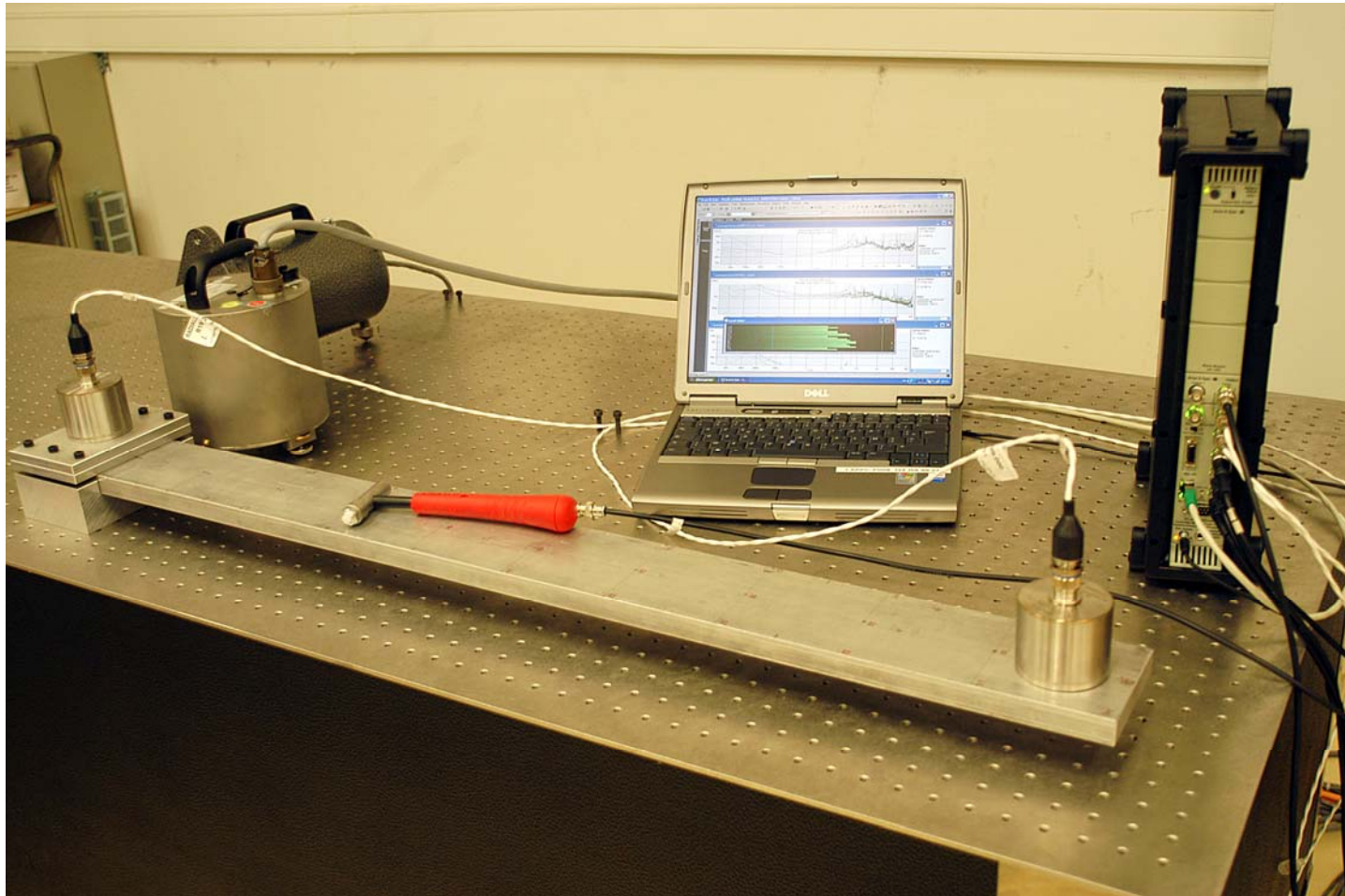
Ground motion
Cooling system
Air flows
Power supply system...

(Amplified motions)



Develop a know-how concerning
modal analysis

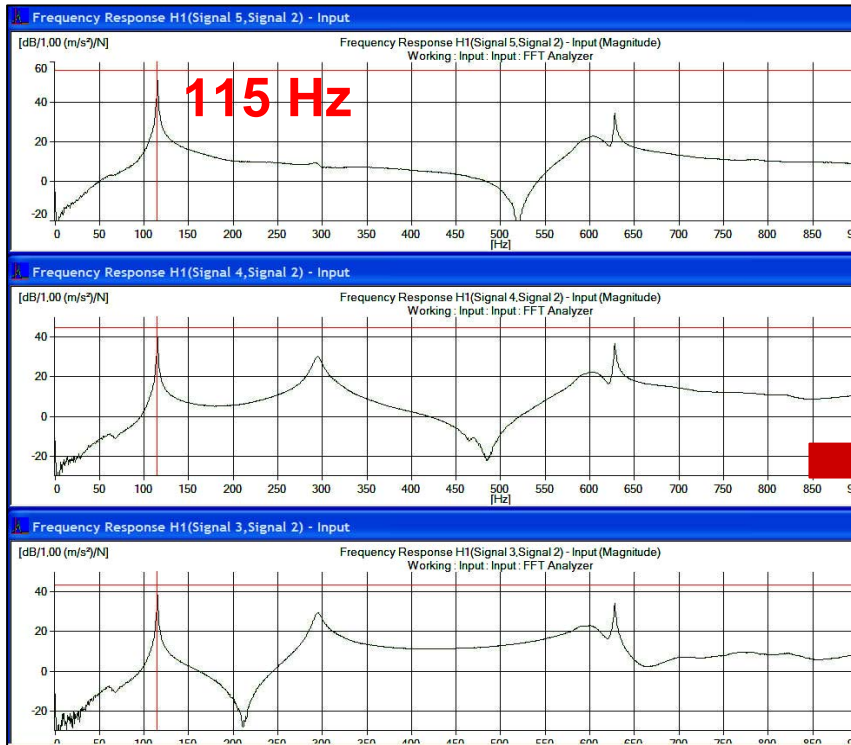
Experimental Modal analysis



Experimental Modal analysis

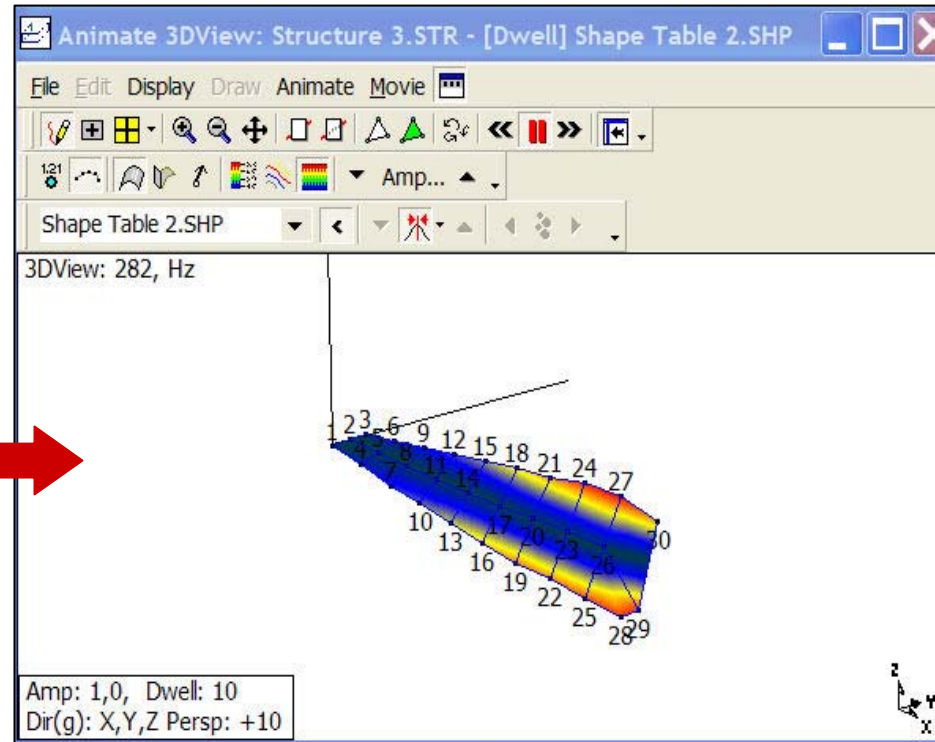
- PULSE**

Fourier transform



- ME' scope**

Mode shape

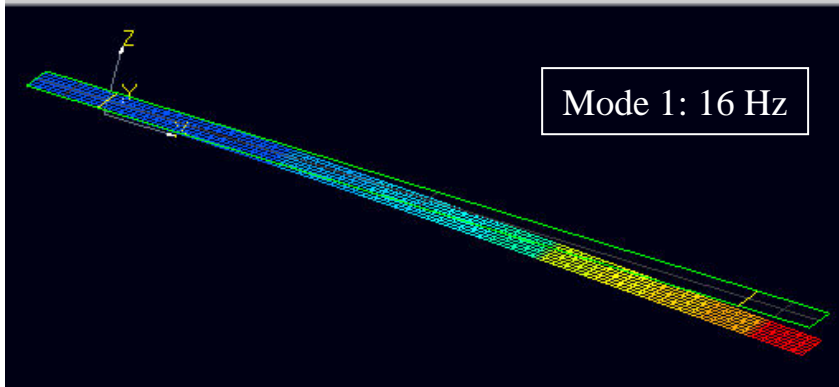


Numerical Modal analysis

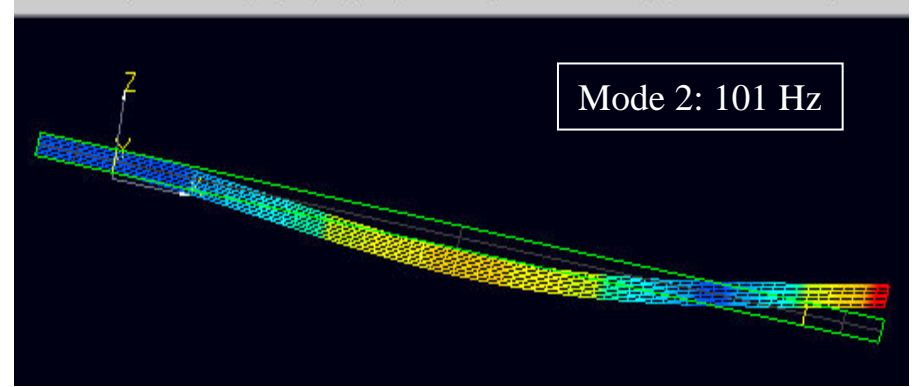
- SAMCEF -

- Identify eigen frequencies
- Display mode shapes

Nodal displacements (DX,DY,DZ) (Displacement, Vibration Mode[1]:16.11397743 Hz)



Nodal displacements (DX,DY,DZ) (Displacement, Vibration Mode[3]:100.9858017 Hz)

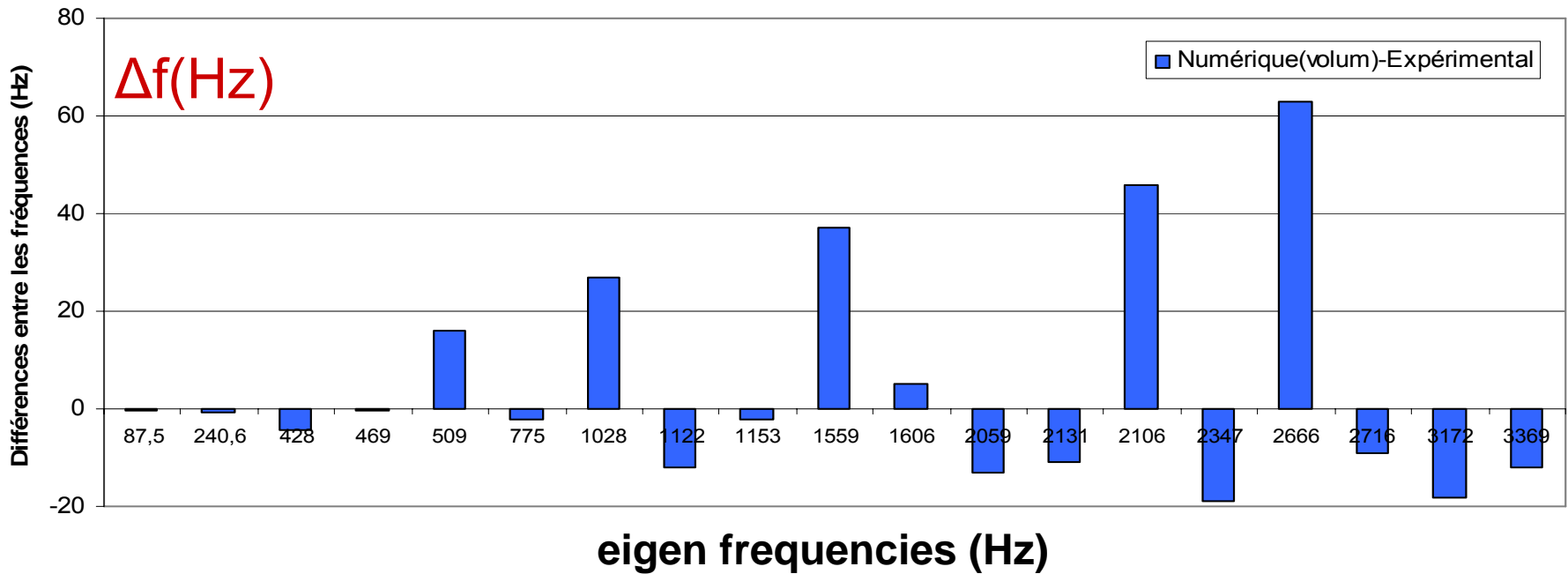


Modal tests on a free-free / free-fixed beam

Preliminary tests - free free -

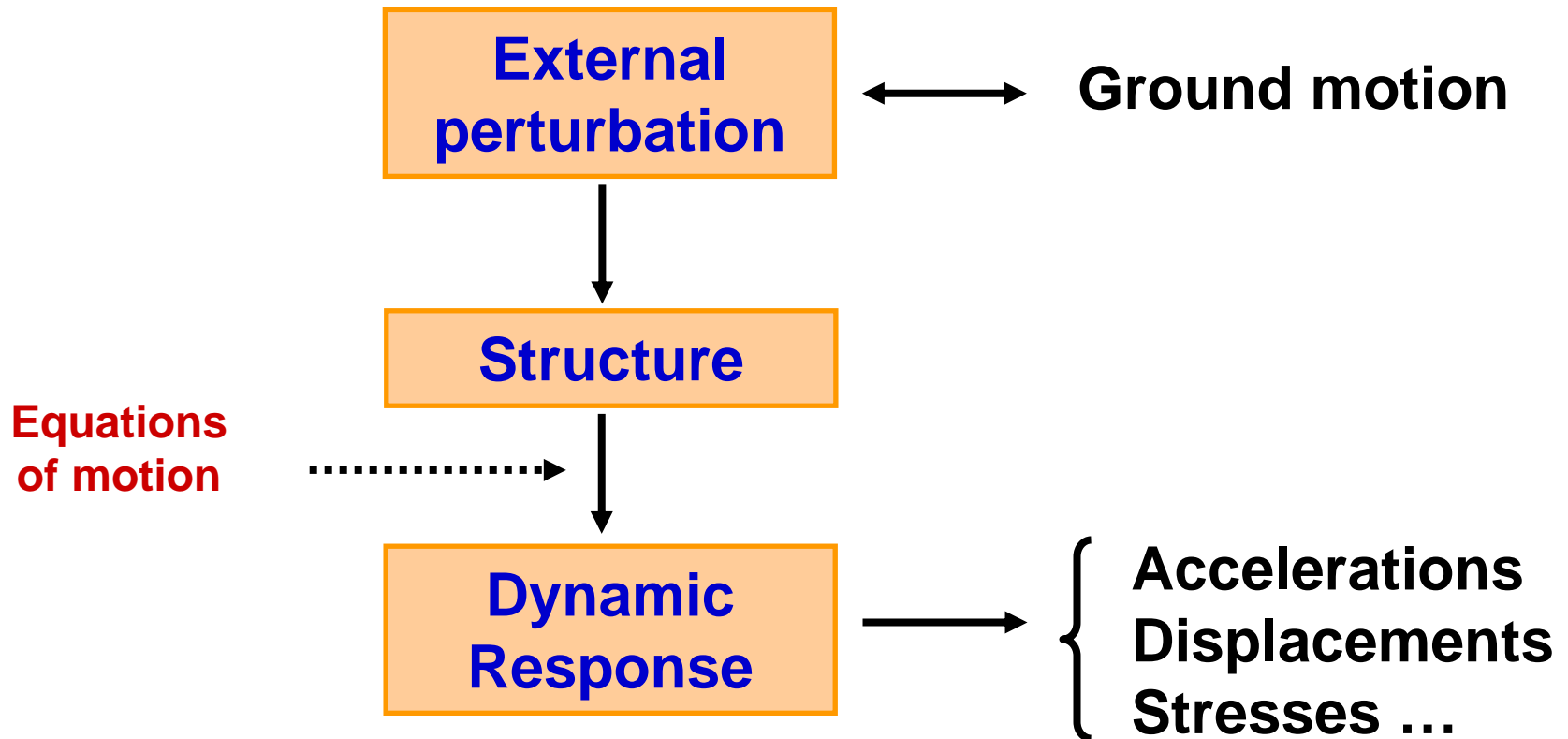


Difference between numerical and experimental eigen frequencies



Good relative accuracy !

Dynamic response



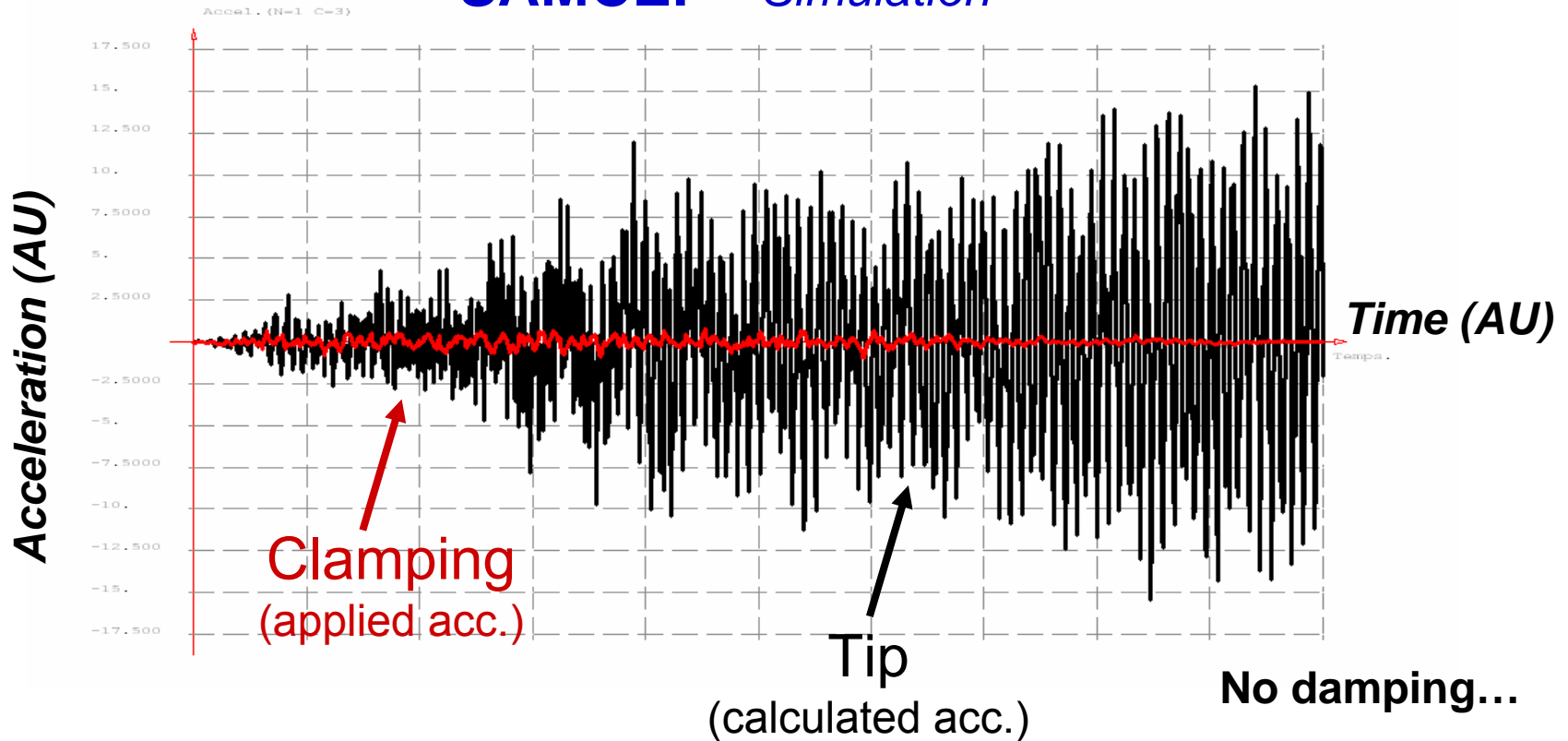
Dynamic response (free-fixed beam)

SAMCEF-BACON: ...YN\poutre_spectre\sp31

14 JUN 2005 15:48:21

Acceleration (ORD.)
 Temps (ABS.)

SAMCEF - Simulation



Dynamic response (free-fixed beam)

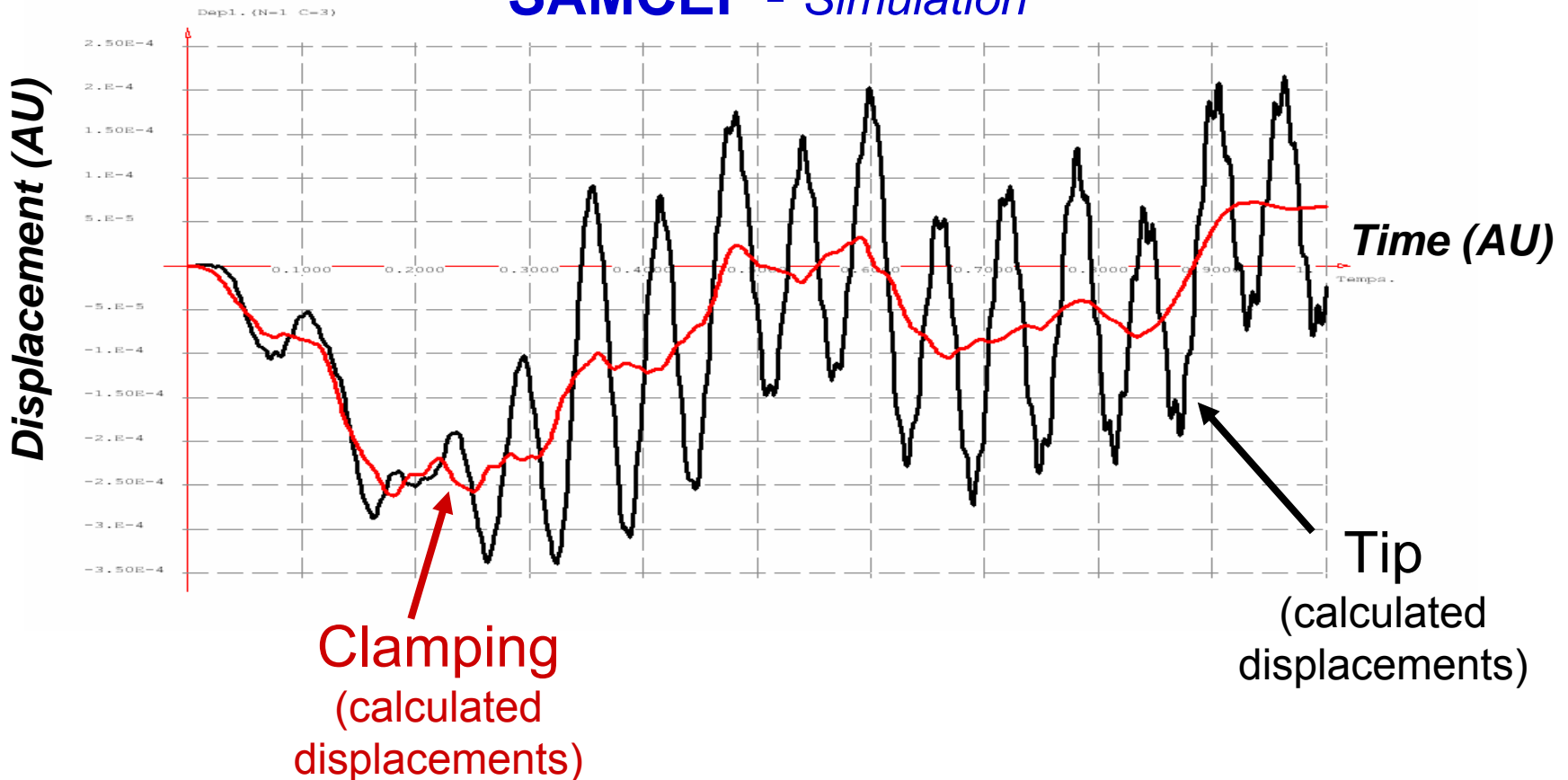
SAMCEF-BACON: ...YN\poutre_spectre\sp31

14 JUN 2005 15:49:56

Deplacement (ORD.)

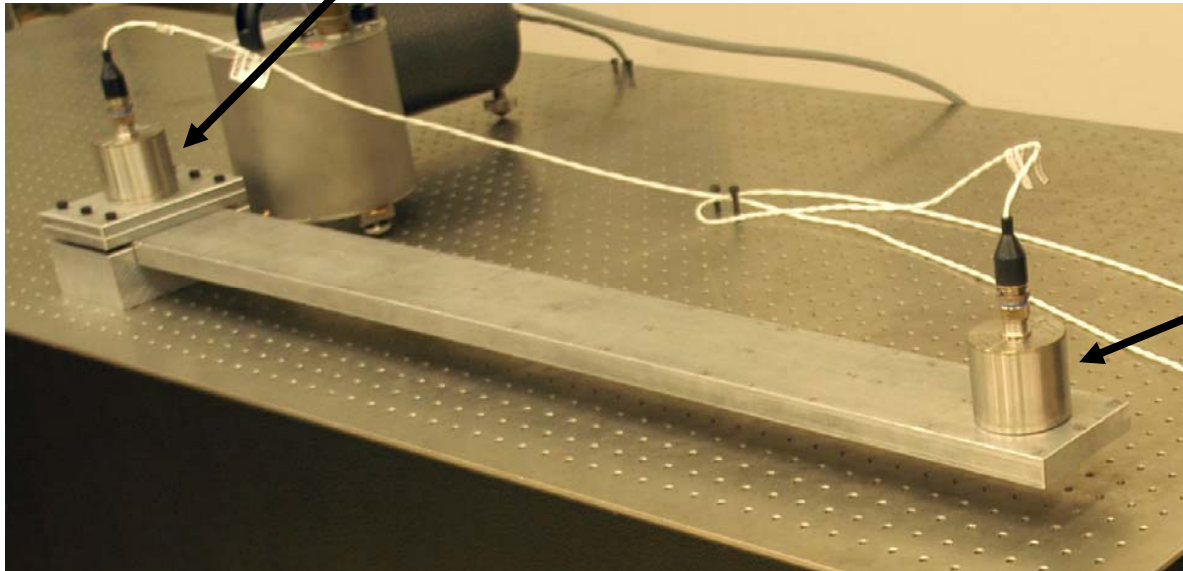
Temps (ABS.)

SAMCEF - Simulation



Dynamic response (free-fixed beam)

Data used as input for the simulation



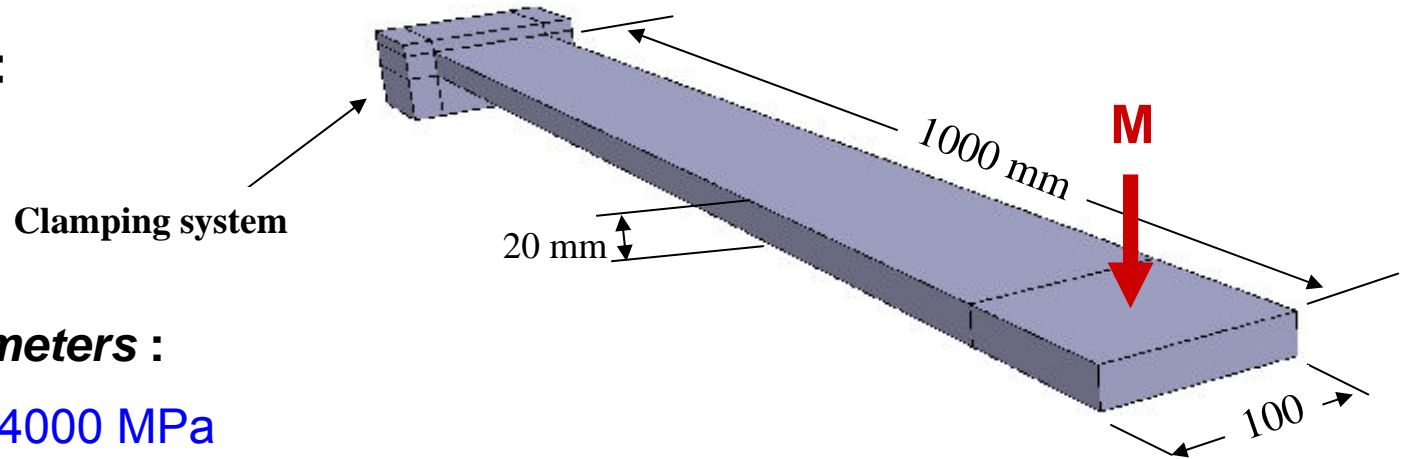
Data used for
the comparison
with simulation



Check the accuracy of the numerical prediction

Dynamic response (free-fixed beam)

Model used :



Beam parameters :

$$E = 74000 \text{ MPa}$$

$$\nu = 0.34 \text{ (Poisson's ratio)}$$

$$\rho = 2825 \text{ kg/m}^3$$

$$\text{Damping : } \varepsilon = 0 \%$$

Lumped mass :

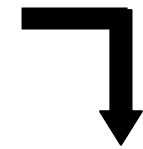
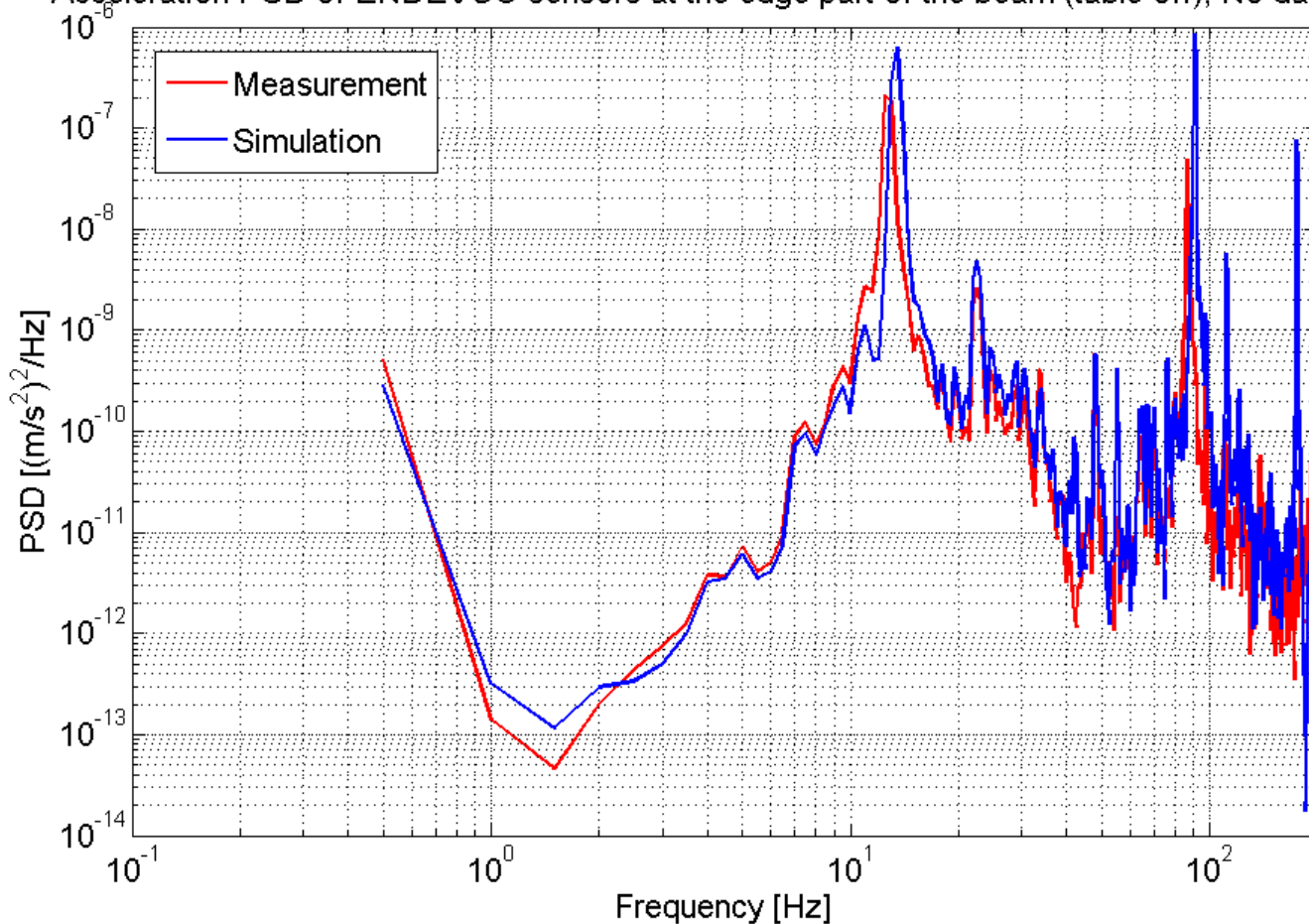
$$M = 830 \text{ g}$$



Structure modeled with “beam” elements

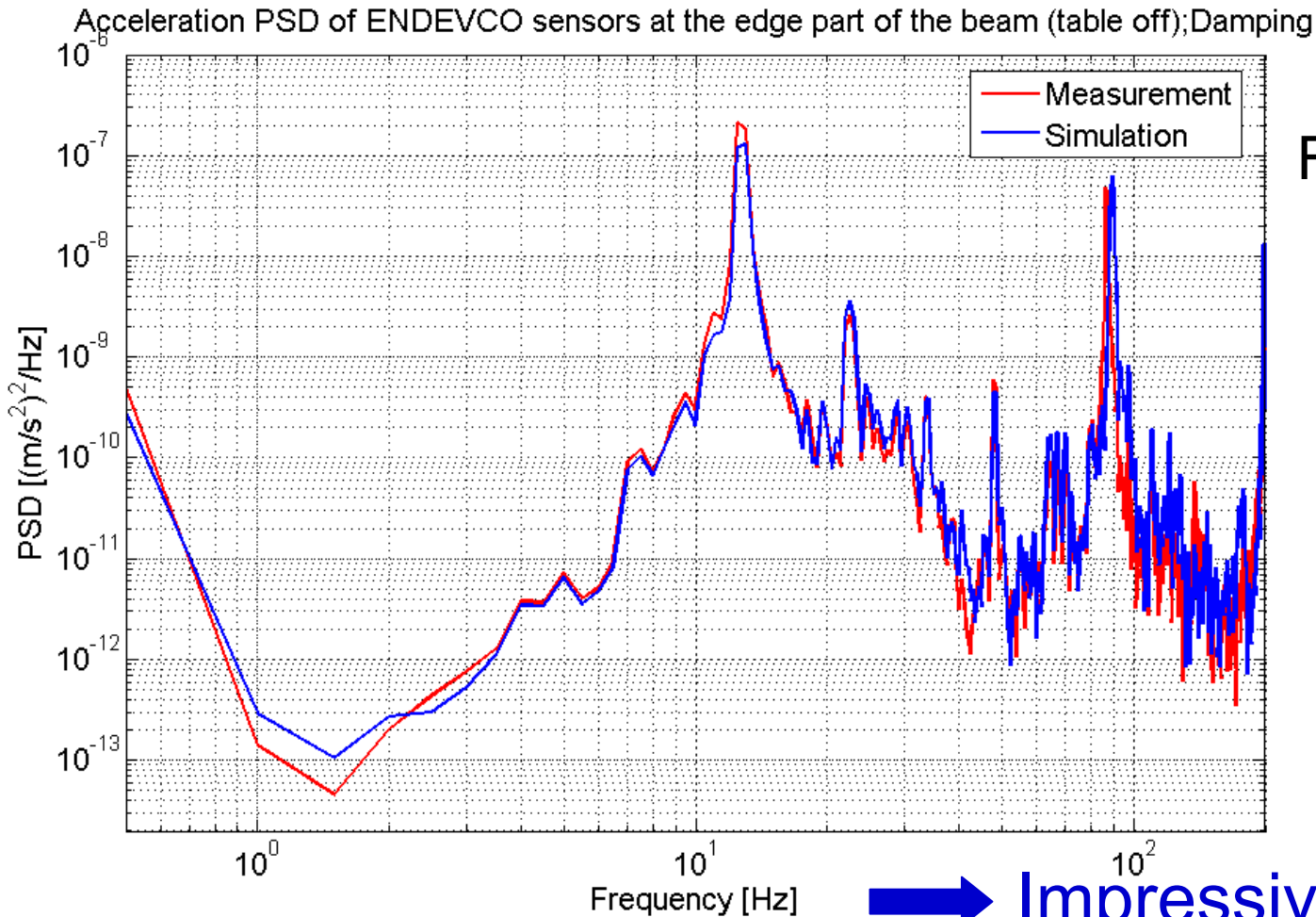
Dynamic response (free-fixed beam)

Acceleration PSD of ENDEVCO sensors at the edge part of the beam (table off); No damping



Good
 agreement

Dynamic response (free-fixed beam)



Fit parameters:

- Stiffness
- Damping
- ...

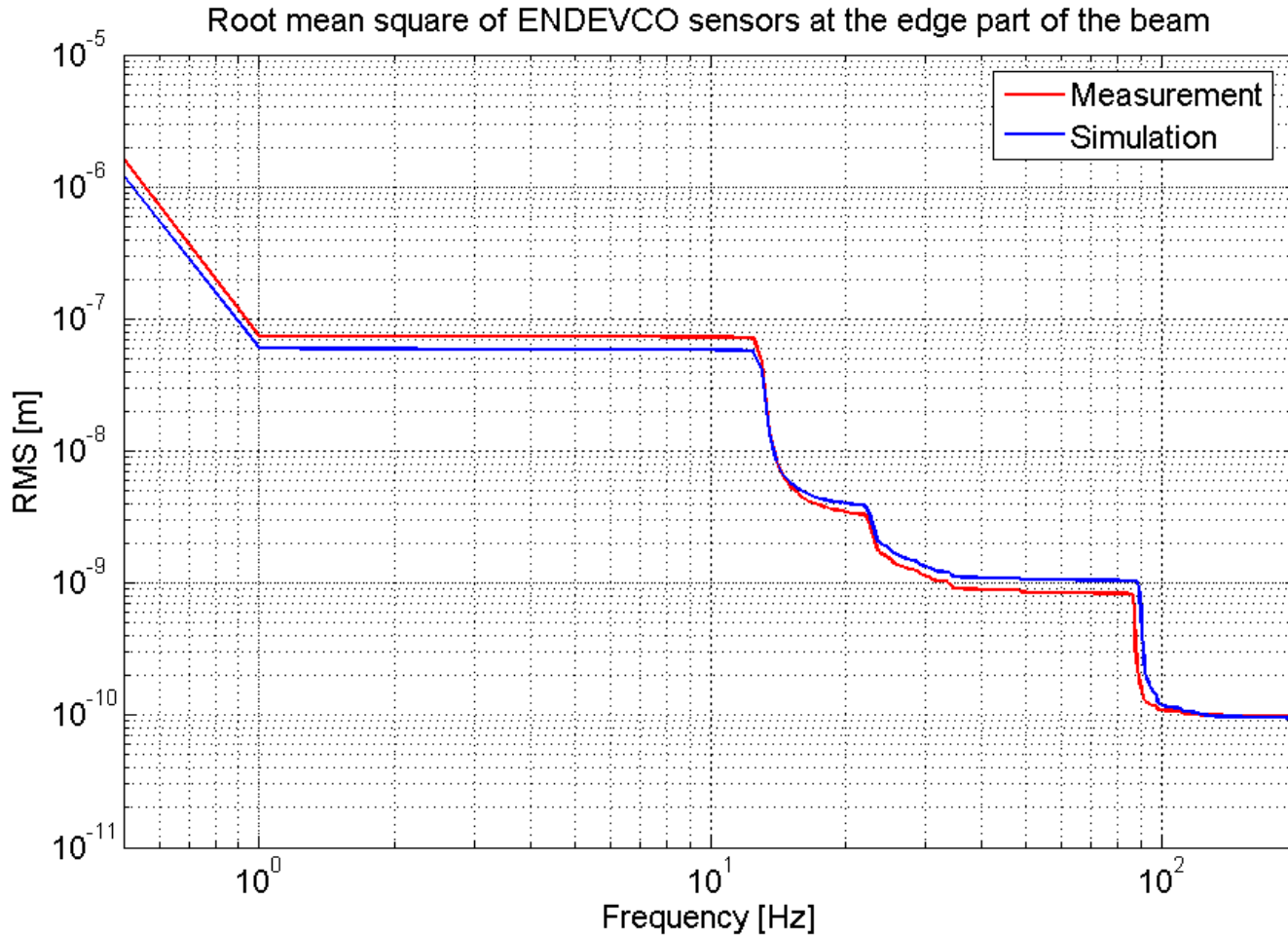


Updated
 FE model



Impressive agreement

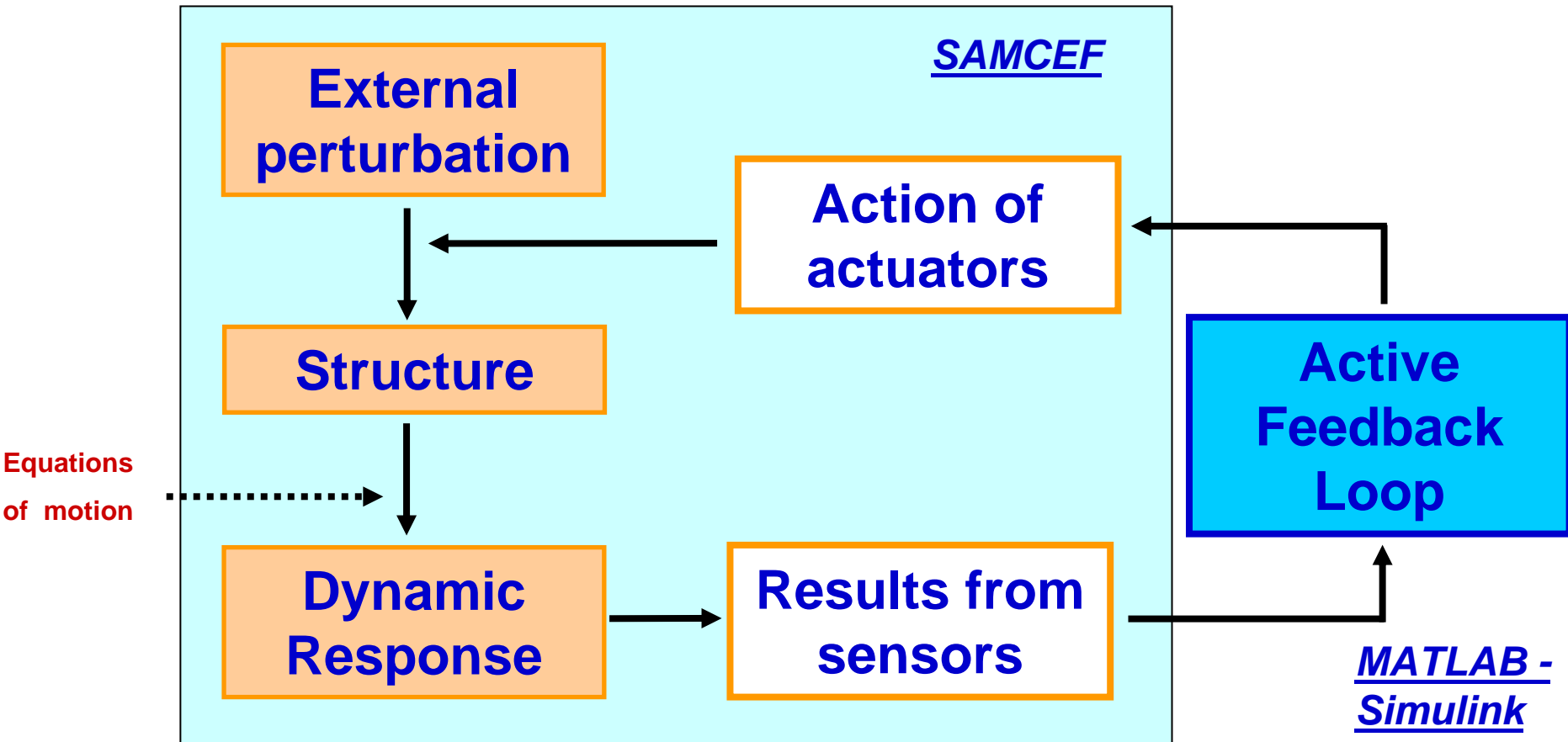
Dynamic response (free-fixed beam)



RMS of the
 updated
 FE model

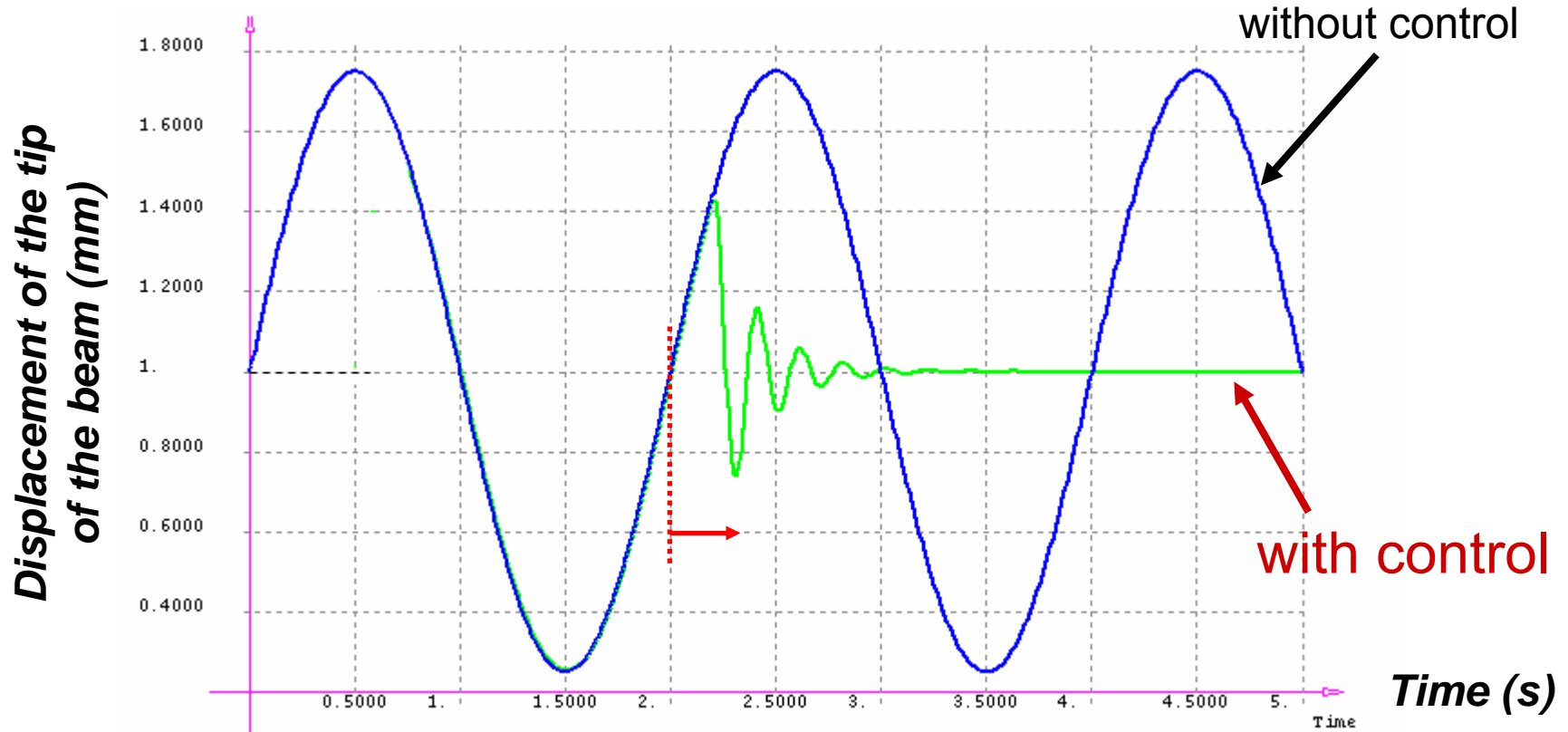
Future prospects

Simulation of the WHOLE SYSTEM:



Future prospects

Simulation of the WHOLE SYSTEM:

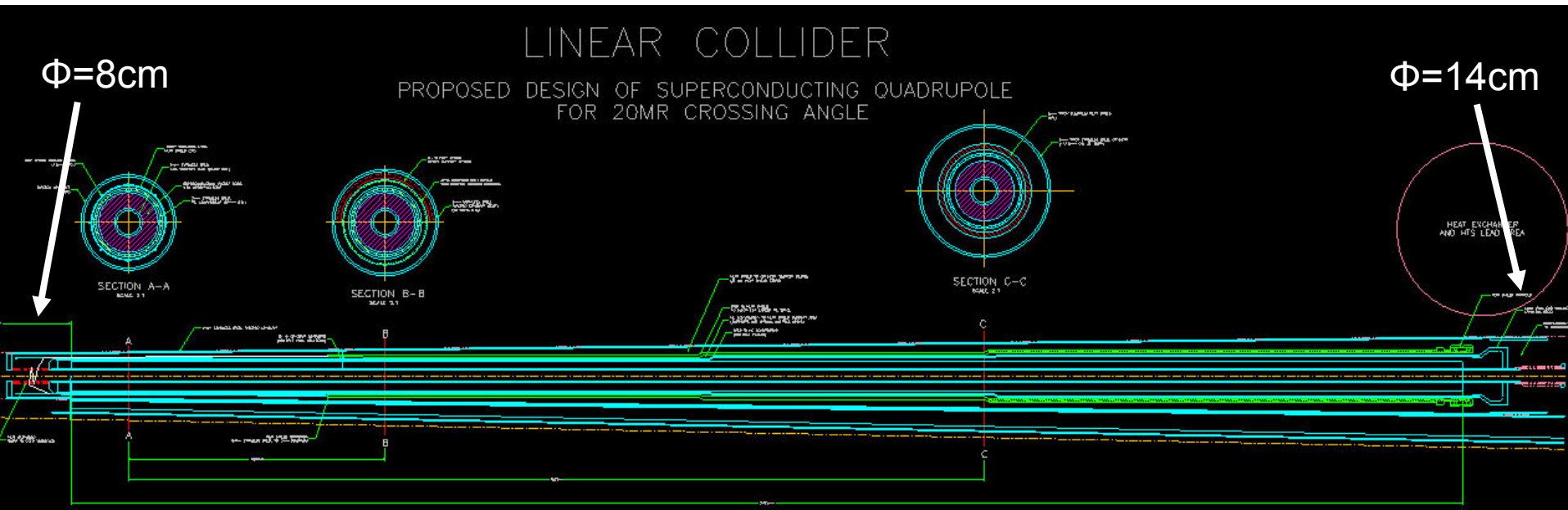


Dynamic response + active control

Future prospects

Prediction concerning the FF quad.

- Computer Aided Design – 1st version



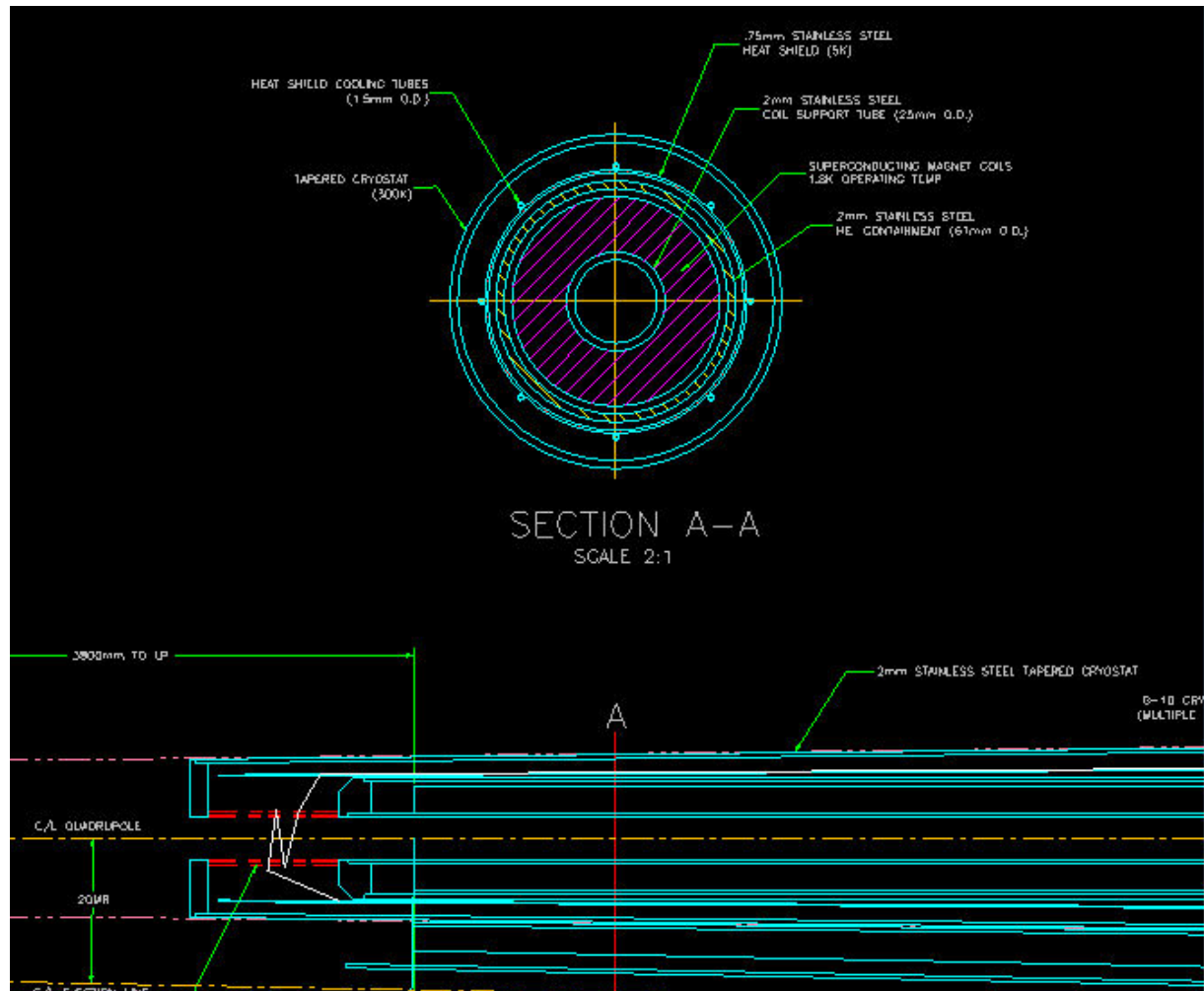
Conical shape - 2.5 meter long

Future prospects

Prediction concerning the FF quad.

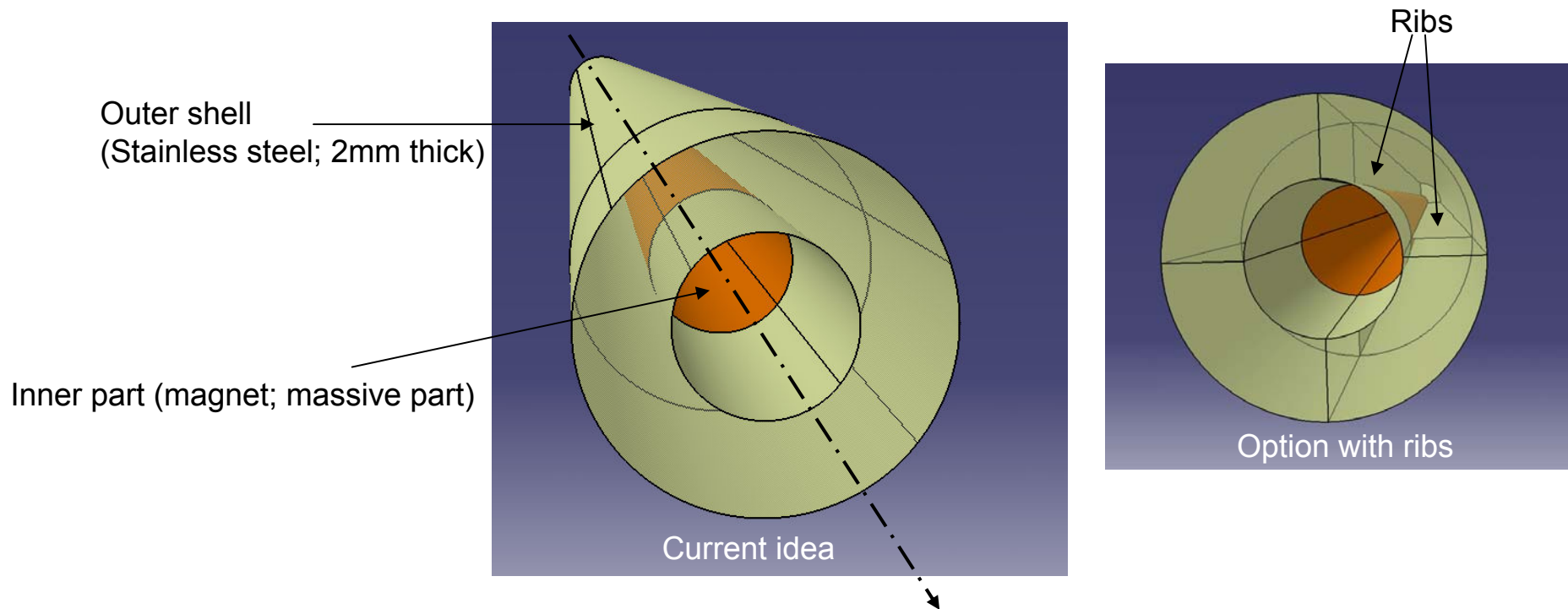
CA Design

1st version



Future prospects

Prediction concerning the FF quad.

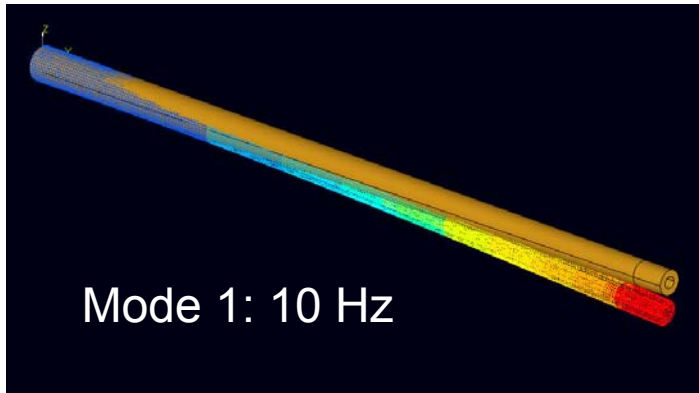


Future prospects

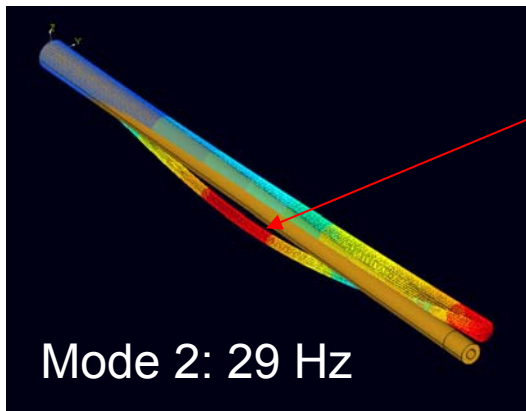
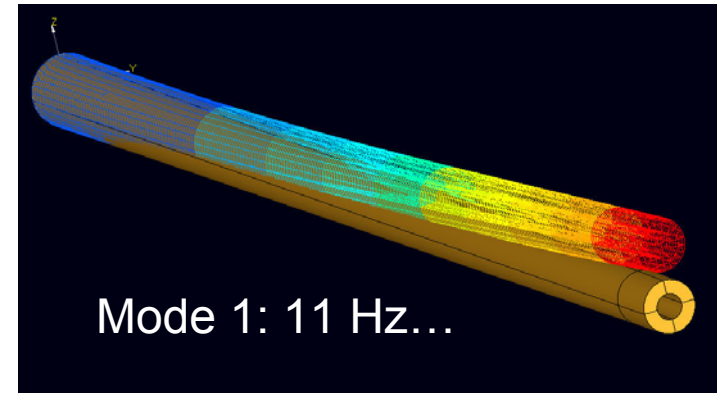
Prediction concerning the FF quad.

Option 1: no inner ribs

Option 2: with inner ribs

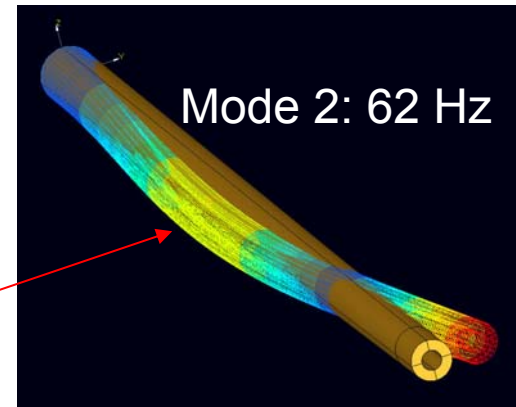


Fixed – Free
 configuration



The magnet is “decoupled”
 to the outer shell ...

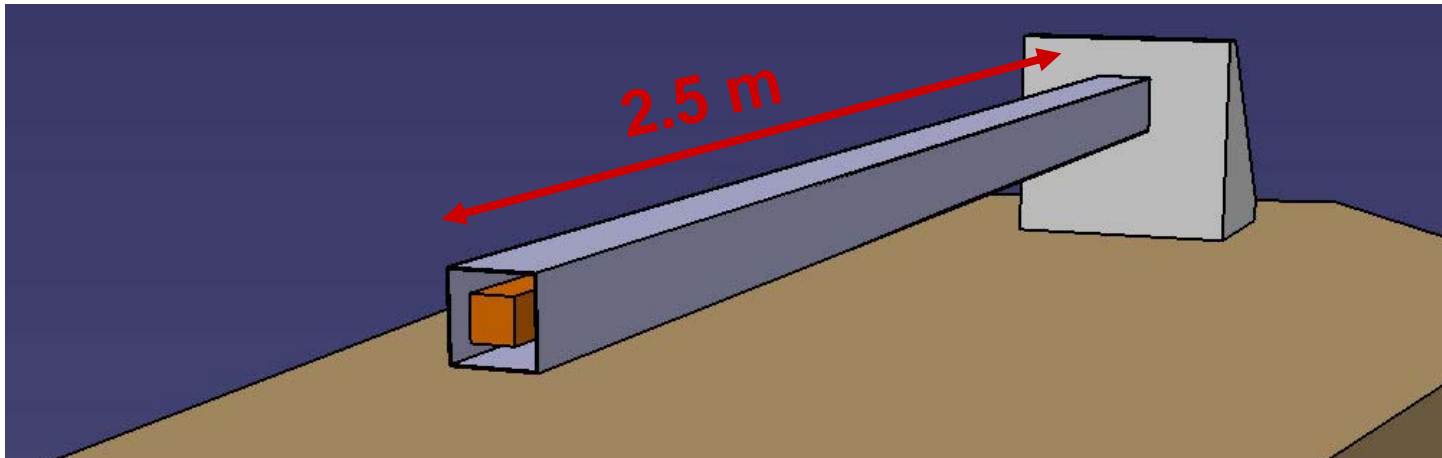
The inner ribs fix the
 magnet to the outer shell



Future prospects

Realization of a new test bench

- Prototype : *fixed-free structure*



- Representative prototype
- Easy Boundary Conditions
- Adaptability

→ { **Eigen frequencies**
Square section
Hollow core (substruc.)

Conclusions

- **Simulate dynamic response of structures**
 - **Check experimentally the accuracy of the models**
 - **Get reliability of the FE models**
- **Simulate modal analysis of the future FF quadrupole**
 - **Propose new design (inner supports ...)**
 - **Propose new materials (composite materials ...)**

Conclusions



Perform simulations of the whole system :

- **Combine simulation of structural dynamics / active control**
 - **Improve efficiency of feedback loop**
 - **Type of sensors / actuators**
 - **Location of sensors / actuators along the structure**
 - **Reliability of the feedback algorithm**
 - ...

Simulation could be a great help !...