Event variable	Description
Object and event kinematics	
$\langle \Delta R_{\mathrm{tag,tag}} \rangle$	Average ΔR between b-tagged jets
$\sum p_{T \text{jets,leptons}}$	Sum of the p_T of all jets and leptons
Tmax mass jet,jet	Twist angle between jet pair
$\min \Delta R_{\text{tag,tag}}$	ΔR between the two closest b-tagged jets
$\max \Delta \eta_{\mathrm{tag,tag}}$	$\Delta\eta$ between the two furthest b-tagged jets
$M_{ m jet,jet}^{{ m min}\Delta R}$	Invariant mass of jet pair with minimum ΔR
$M_{ m higgs-like}^{ m jj}$	Invariant mass of a jet pair ordered in closeness to the Higgs mass
$M_{ ext{tag}, ext{tag}}^{ ext{min}\Delta R}$	Mass of b-tagged jet pair with minimum ΔR
$p_{T \text{ tag,tag}}^{\min \Delta R}$	Sum of the p_T of b-tagged jet pair with minimum ΔR
Centrality (tags)	Ratio of the sum of the transverse momentum of all b-tagged jets and the sum of the energy of all b-tagged jets
Centrality (jets, leptons)	Ratio of the sum of the transverse momentum of all jets and leptons, and the sum of the energy of all jets and leptons
H_T	Scalar sum of transverse momentum for all jets
$\min \Delta R_{\text{jet,jet}}$	ΔR between the two closest jets
median M _{jet,jet}	Median invariant mass of all combinations of jet pairs
M ^{max mass} tag,tag	Mass for b-tagged jet pair with maximum invariant mass combination
$\langle \Delta R_{jet,tag} \rangle$	Average ΔR between jets (with at least one b-tagged jet)
$p_{T \ jet,tag}^{\min\Delta R}$	Sum of the p_T of jet pair with minimum ΔR (with at least one b-tagged jet)
τ _{jet,tag} mass	Twist angle between jet pair (with at least one b-tagged jet)
$m_{ ext{jet,jet}, ext{jet}}^{ ext{max} p_T}$	Invariant mass of the 3-jet system with the largest transverse momentum.
$M_{ m higgs-like}^{ m bj}$	Invariant mass of a jet pair (with at least one b-tagged jet) ordered in closeness to the Higgs mass
CSVv2 b-tag	
$\langle d angle_{ m tagged/untagged}$	Average CSVv2 b-tag discriminant value for b-tagged/un-b-tagged jets
Event shape	
H_0, H_1, H_2, H_3, H_4	Fox-Wolfram moments [?]
C(jets)	$3 (\lambda_1 \lambda_2 + \lambda_1 \lambda_3 + \lambda_2 \lambda_3) [?]$