

Model	ΔLL	
	$B^0 \rightarrow \bar{D}^0 D_s^+ \pi^-$	$B^+ \rightarrow D^- D_s^+ \pi^+$
Default model (One $D_s^+ \pi$ state (0^+))	–	–
Variation of $D_s^+ \pi$ states		
No $D_s^+ \pi$ state	–35	–23
One $D_s^+ \pi$ state (1^-)	–8	–15
One $D_s^+ \pi$ state (2^+)	–27	–15
Two $D_s^+ \pi$ states ($0^+ + 0^+$)	16	11
Two $D_s^+ \pi$ states ($0^+ + 1^-$)	11	7
Additional $D\pi$ states		
$1^- D\pi$ state	5	6
$2^+ D\pi$ state	15	8
$3^- D\pi$ state	6	9
Additional DD_s^+ states		
$0^+ DD_s^+$ state	15	6
$1^- DD_s^+$ state	12	9
$2^+ DD_s^+$ state	6	9