

Syst. uncertainty	$\frac{N(B^0 \rightarrow \pi^+ \pi^-)}{N(B^0 \rightarrow K^+ \pi^-)}$	$\frac{N(B_s^0 \rightarrow K^+ K^-)}{N(B^0 \rightarrow K^+ \pi^-)}$	$\frac{N(\Lambda_b^0 \rightarrow p \pi^-)}{N(\Lambda_b^0 \rightarrow p K^-)}$	$\frac{N(B_s^0 \rightarrow \pi^+ K^-)}{N(B^0 \rightarrow K^+ \pi^-)}$	$\frac{N(B^0 \rightarrow K^+ K^-)}{N(B_s^0 \rightarrow K^+ K^-)}$	$\frac{N(B_s^0 \rightarrow \pi^+ \pi^-)}{N(B^0 \rightarrow \pi^+ \pi^-)}$
PID calibration	0.0002	0.0012	0.0075	0.0013	0.0005	0.0002
Final state rad.	0.0019	0.0043	0.0140	0.0012	0.0093	0.0013
Signal model	negligible	0.0001	0.0013	0.0052	0.0010	0.0031
Comb. bkg model	0.0013	0.0006	0.0086	negligible	0.0012	0.0004
$K\pi$ 3-body bkg	0.0018	0.0048	0.0239	0.0011	negligible	negligible
Cross-feed bkg	0.0023	0.0045	0.0042	0.0008	0.0008	0.0002
Total	0.0038	0.0080	0.0304	0.0056	0.0095	0.0034