Source of uncertainty	$M(B_c^+)$	ΔM
Mass fitting:		
– Signal model	0.1	0.1
– Background model	0.3	0.2
Momentum scale:		
– Average momentum scale	1.4	0.5
– η dependence	0.3	0.1
Detector description:		
– Energy loss correction	0.1	-
Detector alignment:		
– Vertex detector (track slopes)	0.1	-
– Tracking stations	0.6	0.3
Quadratic sum	1.6	0.6